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Robots could take over 20 million manufacturing jobs around the world by 2030, economists claimed Wednesday. According to a new study from Oxford Economics, within the next 11 years there could be ...

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Active in developing robotic solutions, Vanessa Evers (The Netherlands) is a professor of Computer Science at the Human Media Interaction group and Scientific Director of the DesignLab at the University of Twente. She has published almost 200 peer-reviewed publications, is an editor for the International Journal of Social Robotics and a senior editor of the Journal of Human-Robot Interaction.

Of robots and humans - UNESCO
Robot Overlords (originally titled Our Robot Overlords) is a 2014 British independent science fiction film, starring Callan McAuliffe, Ben Kingsley and Gillian Anderson.The film is directed by Jon Wright and produced by Piers Tempest. The estimated budget was $21 million. Robot Overlords - Wikipedia Read Robots (and Human Overl...

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In The Glass Cage, Pulitzer Prize nominee and bestselling author Nicholas Carr shows how the most important decisions of our lives are now being made by machines and the radical effect this is having on our ability to learn and solve problems. In May 2009 an Airbus A330 passenger jet equipped with the latest 'glass cockpit' controls plummeted 30,000 feet into the Atlantic. The reason for the crash: the autopilot had routinely switched itself off. In fact, automation is everywhere – from the thermostat in our homes and the GPS in our phones to the algorithms of High Frequency Trading and self-driving cars. We now use it to diagnose patients, educate children, evaluate criminal evidence and fight wars. But psychological studies show that we perform best when fully involved in a task, while the principle of automation – that humans are inefficient – is self-fulfilling. The glass cockpit is becoming a glass cage. In this utterly engrossing exposé, bestselling writer Nicholas Carr reveals how automation is affecting our ability to solve problems, forge memories and acquire skills. Rather than rejecting technology, Carr argues that we must urgently rethink its role in our lives, using it to enhance rather than diminish the extraordinary abilities that make us human.

"This 50-page report outlines concerns about these fully autonomous weapons, which would inherently lack human qualities that provide legal and non-legal checks on the killing of civilians. In addition, the obstacles to holding anyone accountable for harm caused by the weapons would weaken the law's power to deter future violations"--Publisher's website.

Human–Robot Interaction in Social Robotics explores important issues in designing a robot system that works with people in everyday environments. Edited by leading figures in the field of social robotics, it draws on contributions by researchers working on the Robovie project at the ATR Intelligent Robotics and Communication Laboratories, a world leader in humanoid interactive robotics. The book brings together, in one volume, technical and empirical research that was previously scattered throughout the literature. Taking a networked robot approach, the book examines how robots work in cooperation with ubiquitous sensors and people over telecommunication networks. It considers the use of social robots in daily life, grounding the work in field studies conducted at a school, train station, shopping mall, and science museum. Critical in the development of network robots, these usability studies allow researchers to discover real issues that need to be solved and to understand what kinds of services are possible. The book tackles key areas where development is needed, namely, in sensor networks for tracking humans and robots, humanoids that can work in everyday environments, and functions for interacting with people. It introduces a sensor network developed by the authors and discusses innovations in the Robovie humanoid, including several interactive behaviors and design policies. Exploring how humans interact with robots in daily life settings, this book offers valuable insight into how robots may be used in the future. The combination of engineering, empirical, and field studies provides readers with rich information to guide in developing practical interactive robots.

A remarkable, intense portrait of the robotic subculture and the challenging quest for robot autonomy. The high bay at the Robotics Institute at Carnegie Mellon University is alive and hyper night and day with the likes of Hyperion, which traversed the Antarctic, and Zoe, the world's first robot scientist, now back home. Robot Segways learn to play soccer, while other robots go on treasure hunts or are destined for hospitals and museums. Dozens of cavorting mechanical creatures, along with tangles of wire, tools, and computer innards are scattered haphazardly. All of these zipping and zooming gizmos are controlled by disheveled young men sitting on the floor, folding chairs, or tool cases, or huddled over laptops squinting into displays with manic intensity.

Award-winning author Lee Gutkind immersed himself in this frenzied subculture, following these young roboticists and their bold conceptual machines from Pittsburgh to NASA and to the most barren and arid desert on earth. He makes intelligible their discoveries and stumbling points in this lively behind-the-scenes work.

Soldier-robot teams will be an important component of future battle spaces, creating a complex but potentially more survivable and effective combat force. The complexity of the battlefield of the future presents its own problems. The variety of robotic systems and the almost infinite number of possible military missions create a dilemma for researchers who wish to predict human-robot interactions (HRI) performance in future environments. Human-Robot Interactions in Future Military Operations provides an opportunity for scientists investigating military issues related to HRI to present their results cohesively within a single volume. The issues range from operators interacting with small ground robots and aerial vehicles to supervising large, near-autonomous vehicles capable of intelligent battlefield behaviors. The ability of the human to 'team' with intelligent unmanned systems in such environments is the focus of the volume. As such, chapters are written by recognized leaders within their disciplines and they discuss their research in the context of a broad-based approach. Therefore the book allows researchers from differing disciplines to be brought up to date on both theoretical and methodological issues surrounding human-robot interaction in military environments. The overall objective of this volume is to illuminate the challenges and potential solutions for military HRI through discussion of the many approaches that have been utilized in order to converge on a better understanding of this relatively complex concept. It should be noted that many of these issues will generalize to civilian applications as robotic technology matures. An important outcome is the focus on developing general human-robot teaming principles and guidelines to help both the human factors design and training community develop a better understanding of this nascent but revolutionary technology. Much of the research within the book is based on the Human Research and Engineering Directorate (HRED), U.S. Army Research Laboratory (ARL) 5-year Army Technology Objective (ATO) research program. The program addressed HRI and teaming for both aerial and ground robotic assets in conjunction with the U.S. Army Tank and Automotive Research and Development Center (TARDEC) and the Aviation and Missile Development Center (AMRDEC) The purpose of the program was to understand HRI issues in order to develop and evaluate technologies to improve HRI battlefield performance for Future Combat Systems (FCS). The work within this volume goes beyond the research results to encapsulate the ATO's findings and discuss them in a broader context in order to understand both their military and civilian implications. For this reason, scientists conducting related research have contributed additional chapters to widen the scope of the original research boundaries.

This book focuses on the importance of human factors in the development of safe and reliable unmanned systems. It discusses current challenges such as how to improve the perceptual and cognitive abilities of robots, develop suitable synthetic vision systems, cope with degraded reliability in unmanned systems, predict robotic behavior in case of a loss of communication, the vision for future soldier-robot teams, human-agent teaming, real-world implications for human-robot interaction, and approaches to standardize both the display and control of technologies across unmanned systems. Based on the AHFE 2017 International Conference on Human Factors in Robots and Unmanned Systems, held on July 17–21 in Los Angeles, California, USA, this book is expected to foster new discussion and stimulate new advances in the development of more reliable, safer, and highly functional devices for carrying out automated and concurrent tasks.

Human-robot interaction (HRI) is the study of interactions between people (users) and robots. HRI is multidisciplinary with contributions from the fields of human-computer interaction, artificial intelligence, robotics, speech recognition, and social sciences (psychology, cognitive science, anthropology, and human factors). There has been a great deal of work done in the area of human-robot interaction to understand how a human interacts with a computer. However, there has been very little work done in understanding how people interact with robots. For robots becoming our friends, these studies will be required more and more.

This open access book examines recent advances in how artificial intelligence (AI) and robotics have elicited widespread debate over their benefits and drawbacks for humanity. The emergent technologies have for instance implications within medicine and health care, employment, transport, manufacturing, agriculture, and armed conflict. While there has been considerable attention devoted to robotics/AI applications in each of these domains, a fuller picture of their connections and the possible consequences for our shared humanity seems needed. This volume covers multidisciplinary research, examines current research frontiers in AI/robotics and likely impacts on societal well-being, human robot relationships, as well as the opportunities and risks for sustainable development and peace. The attendant ethical and religious dimensions of these technologies are addressed and implications for regulatory policies on the use and future development of AI/robotics technologies are elaborated.

Social robots not only work with humans in collaborative workspaces we meet them in shopping malls and even more personal settings like health and care. Does this imply they should become more human, able to interpret and adequately respond to human emotions? Do we want them to help elderly people? Do we want them to support us when we are old ourselves? Do we want them to just clean and keep things orderly or would we accept them helping us to go to the toilet, or even feed us if we suffer from Parkinson's disease? The answers to these questions differ from person to person. They depend on cultural background, personal experiences but probably most of all on the robot in question. This book covers the phenomenon of social robots from the historic roots to today's best practices and future perspectives. To achieve this, we used a hands-on, interdisciplinary approach, incorporating findings from computer scientists, engineers, designers, psychologists, doctors, nurses, historians and many more. The book also covers a vast spectrum of applications, from collaborative industrial work over education to sales. Especially for developments with a high societal impact like robots in health and care settings, the authors discuss not only technology, design and usage but also ethical aspects. Thus this book creates both a compendium and a guideline, helping to navigate the design space for future developments in social robotics.

This book aims to discuss the technical and ethical challenges posed by the present technological framework and to highlight the fundamental role played by human-centred design and human factors in the definition of robotic architectures for human–robot collaboration. The book gives an updated overview of the most recent robotic technology, conceived and designed to collaborate with human beings in industrial working scenarios. The technological development of robotics over the last years and the fast evolution of AI, machine learning and IoT have paved the way for applications that extend far beyond the typical use of robots performing repetitive tasks in exclusive spaces. In this new technological paradigm that is expected to drive the robotics market in the coming years, robots and workers will coexist in the same workplace, sharing not only this lived space, but also the roles and functions inherent to a process of production, merging the benefits of automated and manual performing. However, having robots cooperating in real time with workers, responding in a physical, psychological and social adequate way, requires a human-centred design that not only calls for high safety standards regulating the quality of human–robot interaction, but also demands the robot's fine-grained perception and awareness of the dynamics of its surrounding environment, namely the behaviours of their human peers–their expected actions/responses–fostering the necessary collaborative efforts towards the accomplishment of the tasks to be executed.