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Thus, this book will be equally useful for all engineering disciplines and, perhaps, will assist in illustrating the utility of control engineering as a controlled discipline. From the Back

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He earned a master's degree in Mechanical Engineering from the University of Illinois in 1953, and a Ph.D. in Engineering Science from the University of California , Berkeley in 1956. Shortly after receiving his doctorate in 1956, he joined Katsuhiko Ogata is a professor of engineering who was born in Tokyo , Japan ; on January 6 of 1925 .

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For senior or graduate-level students taking a first course in Control Theory (in departments of Mechanical, Electrical, Aerospace, and Chemical Engineering). A comprehensive, senior-level textbook for control engineering. Ogata's Modern Control Engineering, 5/e, offers the comprehensive coverage of continuous-time control systems that all senior students must have, including frequency response approach, root-locus approach, and state-space approach to analysis and design of control systems. The text provides a gradual development of control theory, shows how to solve all computational problems with MATLAB, and avoids highly mathematical arguments. A wealth of examples and worked problems are featured throughout the text. The new edition includes improved coverage of Root-Locus Analysis (Chapter 6) and Frequency-Response Analysis (Chapter 8). The author has also updated and revised many of the worked examples and end-of-chapter problems. This text is ideal for control systems engineers.

This book represents an attempt to organize and unify the diverse methods of analysis of feedback control systems and presents the fundamentals explicitly and clearly. The scope of the text is such that it can be used for a two-semester course in control systems at the level

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of undergraduate students in any of the various branches of engineering (electrical, aeronautical, mechanical, and chemical). Emphasis is on the development of basic theory. The text is easy to follow and contains many examples to reinforce the understanding of the theory. Several software programs have been developed in MATLAB platform for better understanding of design of control systems. Many varied problems are included at the end of each chapter. The basic principles and fundamental concepts of feedback control systems, using the conventional frequency domain and time-domain approaches, are presented in a clearly accessible form in the first portion (chapters 1 through 10). The later portion (chapters 11 through 14) provides a thorough understanding of concepts such as state space, controllability, and observability. Students are also acquainted with the techniques available for analysing discrete-data and nonlinear systems. The hallmark feature of this text is that it helps the reader gain a sound understanding of both modern and classical topics in control engineering.

Designed for a short course on control systems or as a review for the professional engineer, this book provides a lucid introduction to modern control systems topics. The five chapters, “ State-Variable Analysis of Continuous-Time Systems, ” “ Analysis of Discrete-Time Systems, ” “ Stability Analysis of Non-Linear Systems, ” “ Optimal Control, ” and “ Adaptive Control ” have been written to emphasize concepts and provide the basic mathematical derivations. Complete coverage of standard topics, e.g., eigenvalues, eigenvectors, the z-transform, Lyapunov ’ s Method, controllability, observability, etc. are discussed. Numerous examples and exercises have also been included in the book for self-

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study. A CD-ROM with MATLAB applications and third-party simulations provides practical design techniques and observations of real control systems.

Modern Control Systems, 12e, is ideal for an introductory undergraduate course in control systems for engineering students. Written to be equally useful for all engineering disciplines, this text is organized around the concept of control systems theory as it has been developed in the frequency and time domains. It provides coverage of classical control, employing root locus design, frequency and response design using Bode and Nyquist plots. It also covers modern control methods based on state variable models including pole placement design techniques with full-state feedback controllers and full-state observers. Many examples throughout give students ample opportunity to apply the theory to the design and analysis of control systems. Incorporates computer-aided design and analysis using MATLAB and LabVIEW MathScript.

About the book... The book provides an integrated treatment of continuous-time and discrete-time systems for two courses at postgraduate level, or one course at undergraduate and one course at postgraduate level. It covers mainly two areas of modern control theory, namely; system theory, and multivariable and optimal control. The coverage of the former is quite exhaustive while that of latter is adequate with significant provision of the necessary topics that enables a research student to comprehend various technical papers. The stress is on interdisciplinary nature of the subject. Practical control problems from various engineering disciplines have been drawn to illustrate the potential concepts. Most of the

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theoretical results have been presented in a manner suitable for digital computer programming along with the necessary algorithms for numerical computations.

For courses in Control Theory Developing Problem-Solving Skills Through Integrated Design and Analysis The purpose of Dorf's Modern Control Systems, Thirteenth Edition is to present the structure of feedback control theory and to provide a sequence of exciting discoveries. The book demonstrates various real-world, global engineering problems while touching on evolving design strategies like green technology. Some of the themes at-hand include climate change, clean water, sustainability, waste management, emissions reduction, and minimizing energy. Throughout the text, students apply theory to the design and analysis of control systems. The Thirteenth Edition continues to explore the role of and need for automated and precise control systems in green engineering. Key examples of green engineering, such as wind turbine control and the modeling of a photovoltaic generator to achieve maximum power delivery, are discussed in detail. The text is organized around the concept of control systems theory in the context of frequency and time domains. Written to be equally useful for all engineering disciplines, it covers topics such as classical control, employing root locus design, frequency and response design using Bode and Nyquist plots.

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Written by an expert in the field, this concise textbook offers hands-on coverage of modern

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- An introduction to control systems
- State-space representations
- Pole placement via state feedback
- State estimators (observers)
- Non-minimal canonical forms
- Linearization
- Lyapunov stability
- Linear quadratic regulators (LQR)
- Symmetric root locus (SRL)
- Kalman filter
- Linear quadratic gaussian control (LQG)

An updated and refined edition of the original presenting both continuous-time and discrete-time systems. Emphasizes the use of PCs to solve complex control system problems easily and efficiently. Provides a computer-aided learning environment with any commercially available CAD software. Features practical illustrations from various branches of engineering, numerous worked examples and exercises.

This package includes a physical copy of Modern Control Engineering (International Version) by Katsuhiko Ogata, as well as access to MATLAB. For senior or graduate-level students taking a first course in Control Theory (in departments of Mechanical, Electrical, Aerospace,

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and Chemical Engineering). A comprehensive, senior-level textbook for control engineering. Ogata's Modern Control Engineering, 5/e, offers the comprehensive coverage of continuous-time control systems that all senior students must have, including frequency response approach, root-locus approach, and state-space approach to analysis and design of control systems. The text provides a gradual development of control theory, shows how to solve all computational problems with MATLAB, and avoids highly mathematical arguments. A wealth of examples and worked problems are featured throughout the text. The new edition includes improved coverage of Root-Locus Analysis (Chapter 6) and Frequency-Response Analysis (Chapter 8). The author has also updated and revised many of the worked examples and end-of-chapter problems. This text is ideal for control systems engineers.

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