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The 7th edition of this classic text continues to provide the same high quality material seen in previous editions. The text is extensively rewritten with updated prose for content clarity, superb new problems in new application areas, outstanding instruction on drawing free body diagrams, and new electronic

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Separation of the elements of classical mechanics into kinematics and dynamics is an uncommon tutorial approach, but the author uses it to advantage in this two-volume set. Students gain a mastery of kinematics first – a solid foundation for the later study of the free-body formulation of the dynamics problem. A key objective of these volumes, which present a vector treatment of the principles of mechanics, is to help the student gain confidence in transforming problems into appropriate mathematical language that may be manipulated to give useful physical conclusions or specific numerical results. In the first volume, the elements of vector calculus and the matrix algebra are reviewed in appendices. Unusual mathematical topics, such as singularity functions and some elements of tensor analysis, are introduced within the text. A logical and systematic building of well-known kinematic concepts, theorems, and formulas, illustrated by examples and problems, is presented offering insights into both fundamentals and applications. Problems amplify the material and pave the way for advanced study of topics in mechanical design analysis, advanced kinematics of mechanisms and analytical dynamics, mechanical vibrations and controls, and continuum mechanics of solids and fluids. Volume I of Principles of Engineering Mechanics provides the basis for a stimulating and rewarding one-term course for advanced undergraduate and first-year graduate students specializing in mechanics, engineering science, engineering physics, applied mathematics, materials science, and mechanical, aerospace, and civil engineering. Professionals working in related fields of applied mathematics will find it a practical review and a quick reference for questions involving basic kinematics.

Dynamics is the third volume of a three-volume textbook on Engineering Mechanics. It was written with the intention of presenting to engineering students the basic concepts and principles of mechanics in as simple a form as the subject allows. A second objective of this book is to guide the students in their efforts to solve problems in mechanics in a systematic manner. The simple approach to the theory of mechanics allows for the different educational backgrounds of the students. Another aim of this book is to provide engineering students as well as practising engineers with a basis to help them bridge the gaps between undergraduate studies, advanced courses on mechanics and practical engineering problems. The book contains numerous examples and their solutions. Emphasis is placed upon student participation in solving the problems. The contents of the book correspond to the topics normally covered in courses on basic engineering mechanics at universities and colleges. Volume 1 deals with Statics; Volume 2 contains Mechanics of Materials.

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