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can't be accepted till CPU is busy in servicing interrupt. Hence (A) is correct option. Question. 12

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where the problem size is increased with the machine size so that the solution time is the same for sequential and parallel executions.

2.6 a. Say Program P1 consists of n x86 instructions, and hence $1.5 \times n$ MIPS instructions. Computer A operates at 2.5 GHz, i.e. it takes 0.4ns per clock. So

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Examples illustrating the methods and techniques for CAD-based circuit design. The companion website includes a chapter on I/O systems with practical examples that show how to use the Raspberry Pi computer to communicate with peripheral devices such as LCDs, Bluetooth radios, and motors. This book will be a valuable resource for students taking a course that combines digital logic and computer architecture or students taking a two-quarter sequence in digital logic and computer organization/architecture. Covers the fundamentals of digital logic design and reinforces logic concepts through the design of an ARM microprocessor. Features side-by-side examples of the two most prominent Hardware Description Languages (HDLs)—SystemVerilog

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compare the ways each can be used in the design of digital systems. Includes examples throughout the text that enhance the reader ' s understanding and retention of key concepts and techniques. The Companion website includes a chapter on I/O systems with practical examples that show how to use the Raspberry Pi computer to communicate with peripheral devices such as LCDs, Bluetooth radios, and motors. The Companion website also includes appendices covering practical digital design issues and C programming as well as links to CAD tools, lecture slides, laboratory projects, and solutions to exercises.

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